

Texture mapping like it's 1995⁽¹⁾



in Python⁽²⁾



1. Pixel color computation done on CPU;
screen is just a big array of bytes
2. Using numpy (kinda cheating, I know)

Who am I

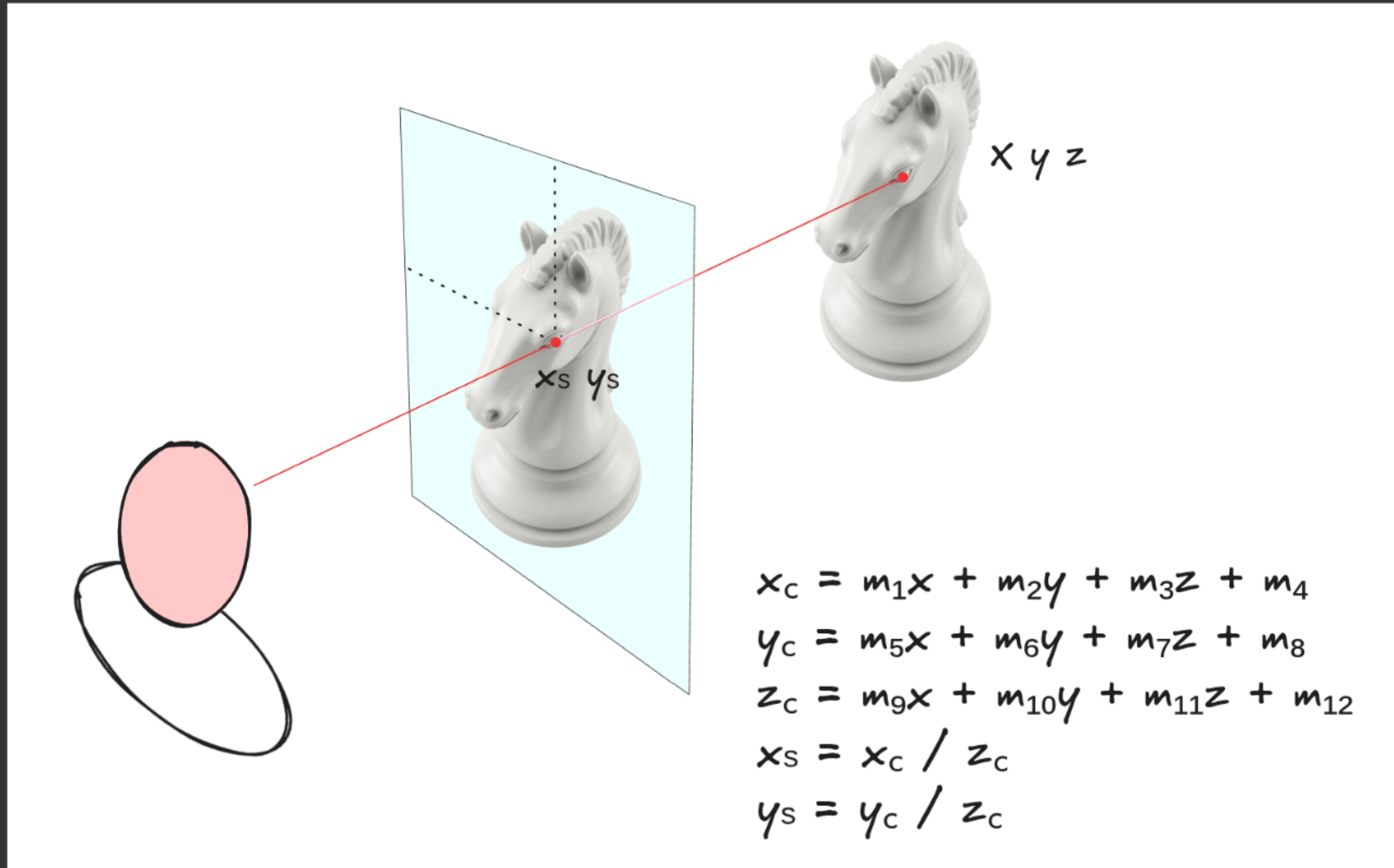


- My name is Andrea "6502" Griffini
- I've been professionally programming for 40+ years in many different fields
- 3d graphics is one of my hobbies
- Back in 1995 it was my job

How it worked back in 1995

- No GPU
- Every pixel on the screen was computed by the CPU
- Single core... only partial parallelism on UV pipelines (required asm coding and the "new" Pentium processor)
- Many tricks were used

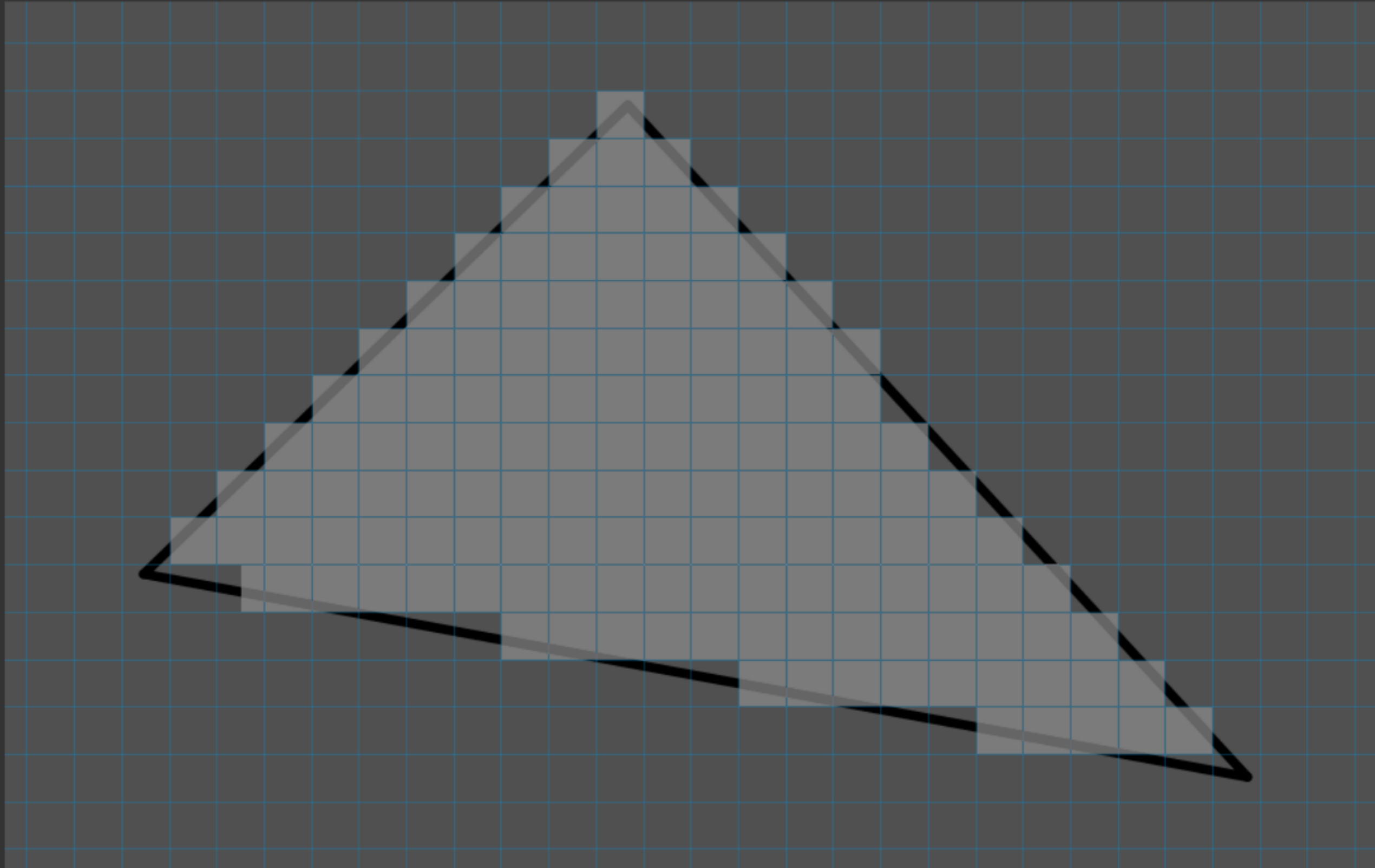
3d → 2d camera mapping



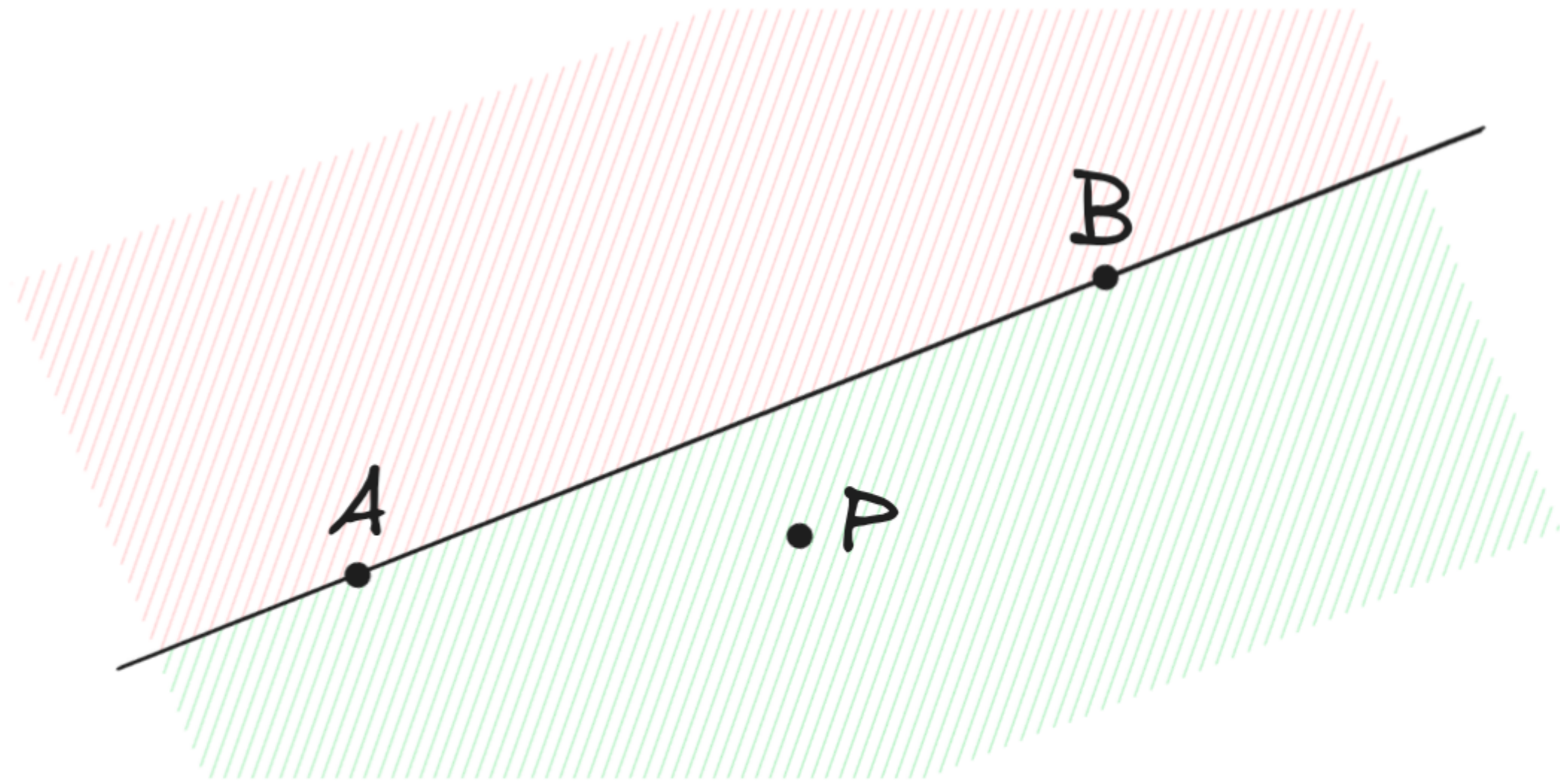
Triangulation



Triangle rasterization



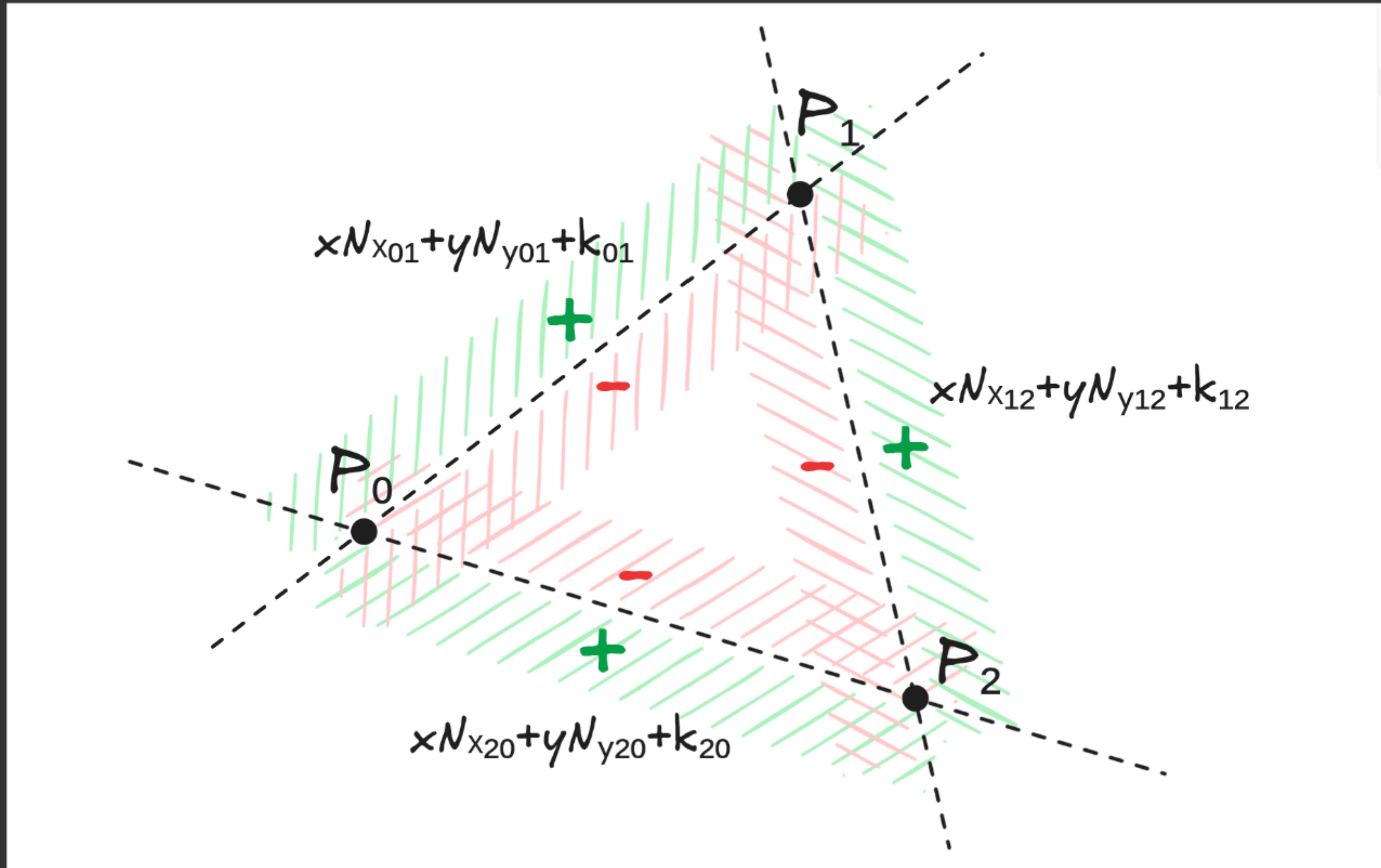
Semiplane equation



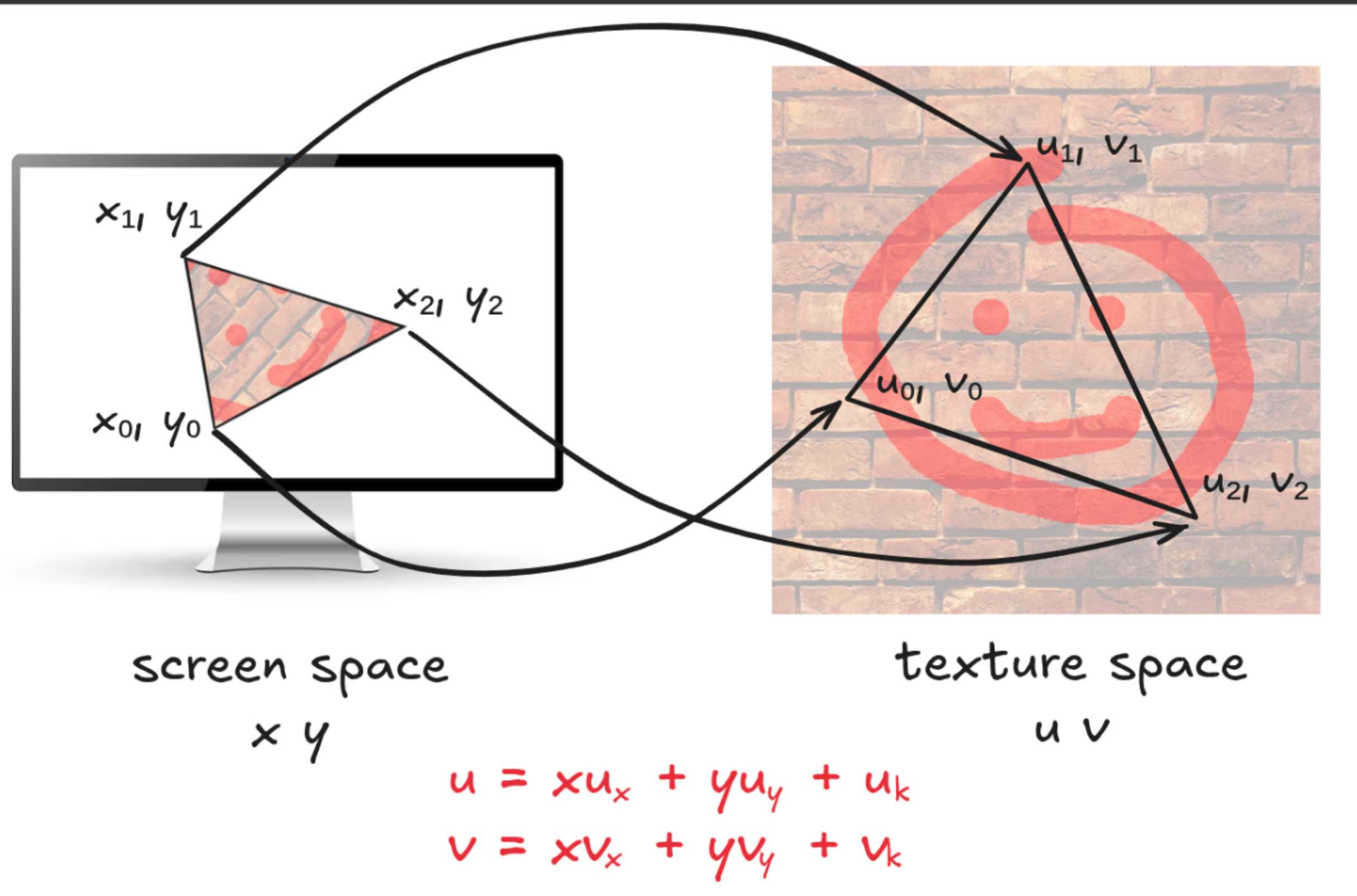
$$(P_x - A_x)(B_y - A_y) - (P_y - A_y)(B_x - A_x) > 0$$

$$N_x P_x + N_y P_y + K > 0$$

Triangle pixels selection



Linear texture mapping



Triangle drawing algorithm

- Project triangle to screen coordinates
- Compute N_x , N_y and k coefficients for each triangle side ($p_0 \rightarrow p_1$, $p_1 \rightarrow p_2$, $p_2 \rightarrow p_0$)
- Compute u_x , u_y , u_k , v_x , v_y , v_k for the triangle
- Find all pixels inside the triangle
- Draw the texture mapped triangle mapping from (x, y) to (u, v) to find the texel to use for each pixel

NumPy to the rescue

1. Can compute the same formula **"in parallel"** on all elements of arrays at the same time
2. Loops are done in C (~**100** times faster than Python loops)
3. Allows indirect access using an array and an array of indices

u_x, u_y, u_k computation

$$\begin{cases} u_x x_0 + u_y y_0 + u_k = u_0 & \text{I} \\ u_x x_1 + u_y y_1 + u_k = u_1 & \text{II} \\ u_x x_2 + u_y y_2 + u_k = u_2 & \text{III} \end{cases}$$

$$\begin{cases} u_x(x_1 - x_0) + u_y(y_1 - y_0) = u_1 - u_0 & \text{II} - \text{I} \\ u_x(x_2 - x_0) + u_y(y_2 - y_0) = u_2 - u_0 & \text{III} - \text{I} \end{cases}$$

$$\Delta = \det \begin{pmatrix} x_1 - x_0 & y_1 - y_0 \\ x_2 - x_0 & y_2 - y_0 \end{pmatrix} = (x_1 - x_0)(y_2 - y_0) - (x_2 - x_0)(y_1 - y_0)$$

$$u_x = \frac{\det \begin{pmatrix} u_1 - u_0 & y_1 - y_0 \\ u_2 - u_0 & y_2 - y_0 \end{pmatrix}}{\Delta} \quad u_y = \frac{\det \begin{pmatrix} x_1 - x_0 & u_1 - u_0 \\ x_2 - x_0 & u_2 - u_0 \end{pmatrix}}{\Delta} \quad u_k = u_0 - u_x x_0 - u_y y_0$$

u_x, u_y, u_k computation

$u_0 + u_x x_0 + u_y y_0 + u_k = u_0$ I
 $u_1 + u_x x_1 + u_y y_1 + u_k = u_1$ II

$A = \pi r^2$
 $C = 2\pi r$

$V = \frac{1}{3} \pi r^2 h$

$V = \pi r^2 h$

	30°	45°	60°
sin	$\frac{1}{2}$	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{3}}{2}$
cos	$\frac{\sqrt{3}}{2}$	$\frac{\sqrt{2}}{2}$	$\frac{1}{2}$
tan	$\frac{\sqrt{3}}{3}$	1	$\sqrt{3}$

$\int \sin x dx = -\cos x + C$
 $\int \frac{dx}{\cos^2 x} = \tan x + C$
 $\int \tan x dx = -\ln|\cos x| + C$
 $\int \frac{dx}{\sin x} = \ln\left|\frac{x}{2}\right| + C$
 $\int \frac{dx}{a^2 + x^2} = \frac{1}{a} \arctan \frac{x}{a} + C$
 $\int \frac{dx}{x^2 - a^2} = \frac{1}{2a} \ln\left|\frac{x-a}{x+a}\right| + C$

$\Delta = \det \begin{pmatrix} u_1 - u_0 & y_1 - y_0 \\ u_2 - u_0 & y_2 - y_0 \end{pmatrix}$

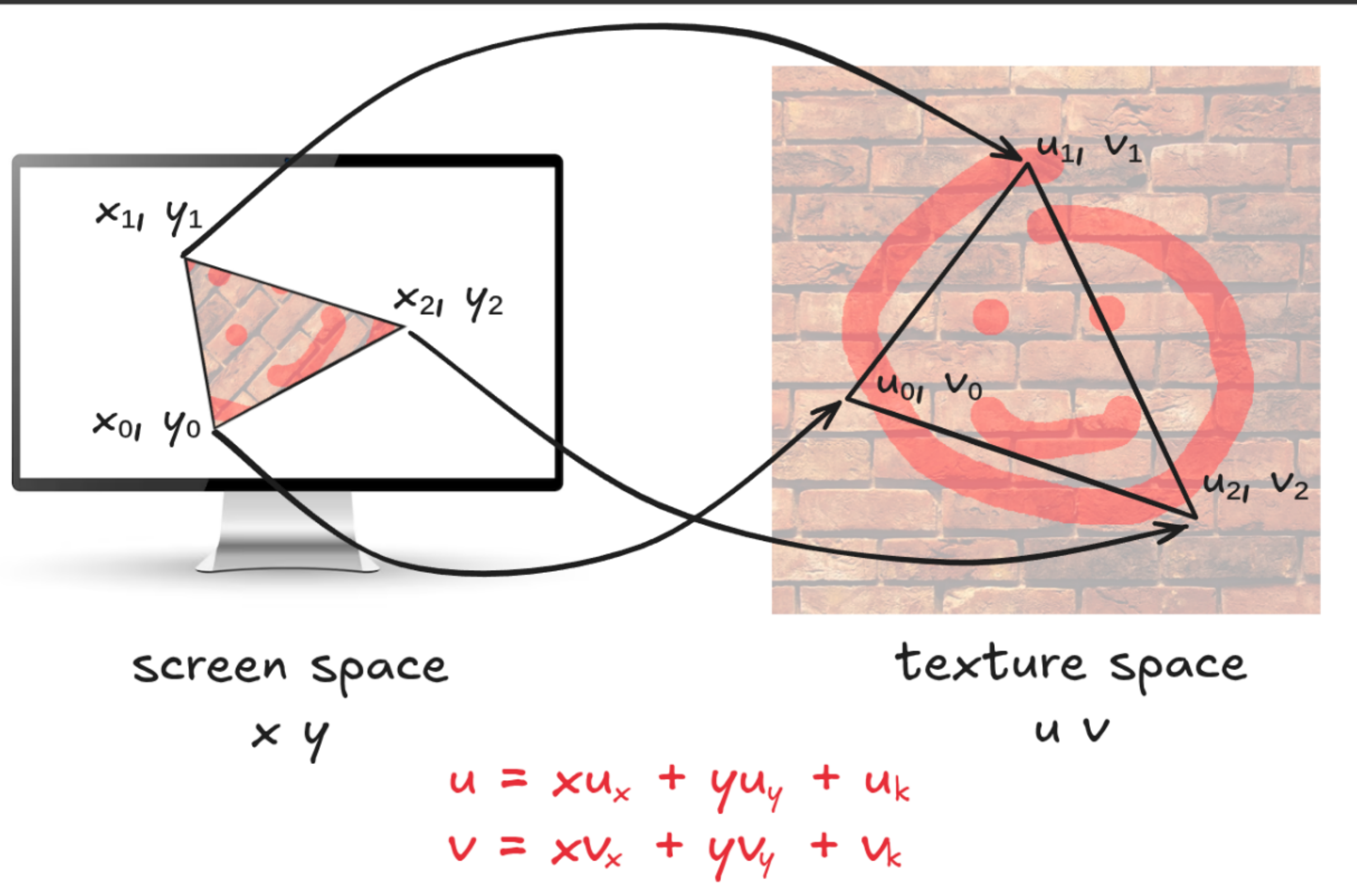
$u_x = \frac{\det \begin{pmatrix} u_1 - u_0 & y_1 - y_0 \\ u_2 - u_0 & y_2 - y_0 \end{pmatrix}}{\Delta}$

$u_y = \frac{\det \begin{pmatrix} u_1 - u_0 & x_1 - x_0 \\ u_2 - u_0 & x_2 - x_0 \end{pmatrix}}{\Delta}$

$u_k = u_0 - u_x x_0 - u_y y_0$

$ax^2 + bx + c = 0$
 $a(x^2 + \frac{b}{a}x + \frac{c}{a}) = 0$
 $x^2 + 2\frac{b}{2a}x + (\frac{b}{2a})^2 - (\frac{b}{2a})^2 + \frac{c}{a} = 0$
 $(x + \frac{b}{2a})^2 - \frac{b^2 - 4ac}{4a^2} = 0$

Linear texture mapping



u_x, u_y, u_k computation

$$\begin{cases} u_x x_0 + u_y y_0 + u_k = u_0 & \text{I} \\ u_x x_1 + u_y y_1 + u_k = u_1 & \text{II} \\ u_x x_2 + u_y y_2 + u_k = u_2 & \text{III} \end{cases}$$

$$\begin{cases} u_x(x_1 - x_0) + u_y(y_1 - y_0) = u_1 - u_0 & \text{II} - \text{I} \\ u_x(x_2 - x_0) + u_y(y_2 - y_0) = u_2 - u_0 & \text{III} - \text{I} \end{cases}$$

$$\Delta = \det \begin{pmatrix} x_1 - x_0 & y_1 - y_0 \\ x_2 - x_0 & y_2 - y_0 \end{pmatrix} = (x_1 - x_0)(y_2 - y_0) - (x_2 - x_0)(y_1 - y_0)$$

$$u_x = \frac{\det \begin{pmatrix} u_1 - u_0 & y_1 - y_0 \\ u_2 - u_0 & y_2 - y_0 \end{pmatrix}}{\Delta} \quad u_y = \frac{\det \begin{pmatrix} x_1 - x_0 & u_1 - u_0 \\ x_2 - x_0 & u_2 - u_0 \end{pmatrix}}{\Delta} \quad u_k = u_0 - u_x x_0 - u_y y_0$$

v_x, v_y, v_k computation

- Identical... but with v instead of u
- Also Δ is the same as for u
(Δ depends only on x/y , not u or v)
- $\Delta=0$ means you've a bad triangle
(vertices are aligned)

Coding time

```
def triangle(x0, y0, u0, v0,
            x1, y1, u1, v1,
            x2, y2, u2, v2,
            L, tx):
    delta = (x1-x0)*(y2-y0) - (x2-x0)*(y1-y0)
    if delta == 0: return
    ux = ((u1-u0)*(y2-y0) - (u2-u0)*(y1-y0)) / delta
    uy = ((x1-x0)*(u2-u0) - (x2-x0)*(u1-u0)) / delta
    uk = u0 - x0*ux - y0*uy
    vx = ((v1-v0)*(y2-y0) - (v2-v0)*(y1-y0)) / delta
    vy = ((x1-x0)*(v2-v0) - (x2-x0)*(v1-v0)) / delta
    vk = v0 - x0*vx - y0*vy

    nx01, ny01 = y1-y0, x0-x1
    nx12, ny12 = y2-y1, x1-x2
    nx20, ny20 = y0-y2, x2-x0
    k01 = -(x0*nx01 + y0*ny01)
    k12 = -(x1*nx12 + y1*ny12)
    k20 = -(x2*nx20 + y2*ny20)

    th, tw = tx.shape[:2]
    xa = max(0, int(min(x0, x1, x2)))
    ya = max(0, int(min(y0, y1, y2)))
    xb = min(w, int(max(x0, x1, x2))+1)
    yb = min(h, int(max(y0, y1, y2))+1)
    Xb = X[ya:yb, xa:xb]
    Yb = Y[ya:yb, xa:xb]
    aab = aa[ya:yb, xa:xb]
    mask = (np.uint8(Xb*nx01 + Yb*ny01 + k01 <= 0) &
            np.uint8(Xb*nx12 + Yb*ny12 + k12 <= 0) &
            np.uint8(Xb*nx20 + Yb*ny20 + k20 <= 0))
    xya = aab[mask == 1]
    xx = X.ravel()[xya]
    yy = Y.ravel()[xya]
    uv = np.int32(xx*vx + yy*vy + vk) & (th-1)
    uv *= tw
    uv += np.int32(xx*ux + yy*uy + uk) & (tw-1)
    img.reshape((w*h, 3))[xya] = np.int32(tx.reshape((tw*th,3))[uv] * L)
```

Coding time

```
def triangle(x0, y0, u0, v0,  
            x1, y1, u1, v1,  
            x2, y2, u2, v2,  
            L, tx):
```

Code: $xy \rightarrow uv$ mapping coefficients

```
delta = (x1-x0)*(y2-y0) - (x2-x0)*(y1-y0)
if delta == 0: return
```

```
ux = ((u1-u0)*(y2-y0) - (u2-u0)*(y1-y0)) / delta
uy = ((x1-x0)*(u2-u0) - (x2-x0)*(u1-u0)) / delta
uk = u0 - x0*ux - y0*uy
```

```
vx = ((v1-v0)*(y2-y0) - (v2-v0)*(y1-y0)) / delta
vy = ((x1-x0)*(v2-v0) - (x2-x0)*(v1-v0)) / delta
vk = v0 - x0*vx - y0*vy
```

Code: sides semiplane equations

```
nx01, ny01 = y1-y0, x0-x1
nx12, ny12 = y2-y1, x1-x2
nx20, ny20 = y0-y2, x2-x0
k01 = -(x0*nx01 + y0*ny01)
k12 = -(x1*nx12 + y1*ny12)
k20 = -(x2*nx20 + y2*ny20)
```

Code: triangle pixels bounding box

```
xa = max(0, int(min(x0, x1, x2)))  
ya = max(0, int(min(y0, y1, y2)))  
xb = min(w, int(max(x0, x1, x2))+1)  
yb = min(h, int(max(y0, y1, y2))+1)
```

Code: numpy arrays for X, Y and pixel address

```
Xb = X[ya:yb, xa:xb]  
Yb = Y[ya:yb, xa:xb]  
aab = aa[ya:yb, xa:xb]
```

numpy   

Code: find all pixels inside triangle

```
mask = (np.uint8(Xb*nx01 + Yb*ny01 + k01 <= 0) &  
        np.uint8(Xb*nx12 + Yb*ny12 + k12 <= 0) &  
        np.uint8(Xb*nx20 + Yb*ny20 + k20 <= 0))
```

numpy



Code: find their x/y/address

```
xya = aab[mask == 1]  
xx = X.ravel()[xya]  
yy = Y.ravel()[xya]
```

numpy   

Code: $xy \rightarrow uv$ & texels address

```
uv = np.int32(xx*vx + yy*vy + vk) & (th-1)  
uv *= tw  
uv += np.int32(xx*ux + yy*uy + uk) & (tw-1)
```

numpy   

Code: draw triangle pixels

```
img.reshape((w*h, 3))[xya] = (  
    np.int32(tx.reshape((tw*th, 3))[uv] * L)  
)
```

numpy   

Demo time

Questions?

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